Software Engineering For Embedded Systems Chapter 11 Optimizing Embedded Software For Performance

Input and output (I/O) devices are very important components in embedded systems. I/O diversity makes I/O management in embedded systems a very complicated process. One of the basic functions of an embedded operating system is to control and manage all of the I/O devices, and to coordinate multiple processes accessing I/O devices simultaneously. The key function for device management is to control I/O implementation between the CPU and the devices. The operating system must send commands to the devices, respond to interrupts and handle exceptions from the devices. It should also provide a simple and easy-to-use interface between the devices and other parts of the system. The I/O management module needs to improve parallel processing capabilities between the CPU and I/O devices as well between I/O devices. To get the best utilization efficiency of the system resources, I/O management should provide a unified, transparent, independent and scalable I/O interface.

Storage in this book refers to external storage devices such as NOR/NAND flash, eSDHC, U-Disk, HDD and SSD, which are commonly used in embedded systems. With the recent development of cloud computing, storage technology plays an increasingly important role in systems. This chapter will discuss data transfer modes between CPU and I/O devices, interrupt technology, I/O control processes and the corresponding device driver implementation process. The programming model of storage devices is also discussed, including feature support and performance optimization.

Linux continues to grow as an operating system of choice in many embedded systems such as networking, wireless, and base stations. In this chapter we look at possible uses of Linux in embedded systems. The chapter covers getting a Linux kernel set up, getting started with creating your Linux baseline, and the initial steps of getting an application running on the platform. If you haven't used Linux for an embedded system before, this chapter will cover all of the basic steps to get you going!

One of the most important considerations in the product life-cycle of an embedded project is to understand and optimize the power consumption of the device. Power consumption is highly visible for hand-held devices which require battery power to be able to guarantee certain minimum usage/idle times between recharging. Other main embedded applications, such as medical equipment, test, measurement, media, and wireless base stations, are very sensitive to power as well - due to the need to manage the heat dissipation of increasingly powerful processors, power supply cost, and energy consumption cost – so the fact is that power consumption cannot be overlooked. The responsibility for setting and keeping power requirements often falls on the shoulders of hardware designers, but the software programmer has the ability to provide a large contribution to power optimization. Often, the impact that the software engineer has on the power consumption of a device is overlooked or underestimated. The goal of this chapter is to discuss how software can be used to optimize power consumption, starting with the basics of what power consumption consists of, how to properly measure power consumption, and then moving on to techniques for minimizing power consumption in software at the algorithmic level, hardware level, and data-flow level. This will include demonstrations of the various techniques and explanations of both how and why certain methods are effective at reducing power so the reader can take and apply this work to their application immediately.

This chapter provides information to successfully organize and manage any embedded software project or program. It introduces quality systems, the OSI model of architecting software into stacks, several software development models and ways in which teams may be organized, and overviews communications. Managing the constraints of scope, schedule, costs including resources, quality, and customer satisfaction fully addresses all the work and activities of any project or program. The natural progression of software development from its concept through its life-cycle until release is discussed. Tools are presented for successful planning and execution of resource management, risk management, problem solving, and the traceability of work extending from requirements to respective engineering responses to testing against those software specifications.

This book integrates new ideas and topics from real time systems, embedded systems, and software engineering to give a complete picture of the whole process of developing software for real-time embedded applications. You will not only gain a thorough understanding of concepts related to microprocessors, interrupts, and system boot process, appreciating the importance of real-time modeling and scheduling, but you will also learn software engineering practices such as model documentation, model analysis, design patterns, and standard conformance. This book is split into four parts to help you learn the key concept of embedded systems; Part one introduces the development process, and includes two chapters on microprocessors and interrupts—fundamental topics for software engineers; Part two is dedicated to modeling techniques for real-time systems; Part three looks at the design of software architectures and Part four covers software implementations, with a focus on POSIX-compliant operating systems. With this book you will learn: The pros and cons of different architectures for embedded systems POSIX real-time extensions, and how to develop POSIX-compliant real time applications How to use real-time UML to document system designs with timing constraints The challenges and concepts related to cross-development Multitasking design and inter-task communication techniques (shared memory objects, message queues, pipes, signals) How to use kernel objects (e.g. Semaphores, Mutex, Condition variables) to address resource sharing issues in RTOS applications The philosophy underpinning the notion of "resource manager" and how to implement a virtual file system using a resource manager The key principles of real-time scheduling and several key algorithms Coverage of the latest UML standard (UML 2.4) Over 20 design patterns which represent the best practices for reuse in a wide range of real-time embedded systems Example codes which have been tested in QNX—a real-time operating system widely adopted in industry

A unique feature of this textbook is to provide a comprehensive introduction to the fundamental knowledge in embedded systems, with applications in cyber-physical systems and the Internet of things. It starts with an introduction to the field and a survey of specification models and languages for embedded and cyber-physical systems. It provides a brief overview of hardware devices used for such systems and presents the essentials of system software for embedded systems, including real-time operating systems. The author also discusses evaluation and validation techniques for embedded systems and provides an overview of techniques for mapping applications to execution platforms, including multi-core platforms. Embedded systems have to operate under tight constraints and, hence, the book also contains a selected set of optimization techniques, including software optimization techniques. The book closes with a brief survey on testing. This third edition has been updated and revised to reflect new trends and technologies, such as the importance of cyber-physical systems and the Internet of things, the evolution of single-
core processors to multi-core processors, and the increased importance of energy efficiency and thermal issues. This chapter provides some guidelines that are commonly used in embedded software development. It starts with principles of programming, including readability, testability, and maintainability. The chapter then proceeds with discussing how to start an embedded software project, including considerations for hardware, file organization, and development guidelines. The focus then shifts to programming guidelines that are important to any software development project, which includes the importance of a syntax coding standard. The chapter concludes with descriptions of variables and definitions and how they are typically used in an embedded software project.


An embedded system is a computer system designed for a specific function within a larger system, and often has one or more real-time computing constraints. It is embedded as part of a larger device which can include hardware and mechanical parts. This is in stark contrast to a general-purpose computer, which is designed to be flexible and meet a wide range of end-user needs. The methods, techniques, and tools for developing software systems that were successfully applied to general purpose computing are not as readily applicable to embedded computing. Software systems running on networks of mobile, embedded devices must exhibit properties that are not always required of more traditional systems such as near-optimal performance, robustness, distribution, dynamism, and mobility. This chapter will examine the key properties of mobile, embedded systems, the resources they consume, and the tradeoffs between performance and resource consumption. Techniques for optimizing embedded software engineering methods are addressed and techniques (e.g., software design, component-based development, software architecture, system integration and test) are also discussed in the context of this domain. This chapter will overview embedded and real-time systems. Nowadays embedded and real-time systems contain complex software. The complexity of embedded systems is increasing, and the amount and variety of software in the embedded products are growing. This creates a big challenge for embedded and real-time software development processes and there is a need to develop separate metrics and benchmarks. “Embedded and Real Time System Development: A Software Engineering Perspective: Concepts, Methods and Principles” presents practical as well as conceptual knowledge of the latest tools, techniques and methodologies of embedded software engineering and real-time systems. Each chapter includes an in-depth investigation regarding the actual or potential role of software engineering tools in the context of the embedded system and real-time system. The book presents state-of-the-art and future perspectives with industry experts, researchers, and academicians sharing ideas and experiences including surrounding frontiers, breakthroughs, innovative solutions and applications. The book is organized into four parts “Embedded Software Development Process”, “Design Patterns and Development Methodology”, “Modelling Framework” and “Performance Analysis, Power Management and Deployment” with altogether 12 chapters. The book is aiming at (i) undergraduate students and postgraduate students conducting research in the areas of embedded software engineering and real-time systems; (ii) researchers at universities and other institutions working in these fields; and (iii) practitioners in the R&D departments of embedded system. It can be used as an advanced reference for a course taught at the postgraduate level in embedded software engineering and real-time systems. This chapter discusses the interface that hardware provides for the embedded software. It discusses the registers and interrupts that provide that interface. But there is more; there are the human aspects of getting the hardware team and the embedded software team to collaborate on the project. Collaboration is needed during the design phase, the co-development phase, the integration phase, and the debugging phase and this chapter discusses those concepts. Several hardware design aspects are discussed that improve the quality of the product and software design aspects are discussed to help support hardware versions. The software architecture of embedded computing systems is a depiction of the system as a set of structures that aids in the reasoning and understanding of how the system will behave. Software architecture acts as the blueprint for the system as well as the project developing it. The architecture is the primary framework of important embedded system qualities such as performance, modifiability, and security, none of which can be achieved without a unifying architectural vision. Architecture is an artifact for early analysis to ensure that a design approach will lead to an acceptable system. This chapter will discuss the details of these aspects of embedded software architectures. Optimization metrics for compiled code are not always measured in resulting execution clock cycles on the target architecture. Consider a modern cellular telephone or wireless device which may download executable over a wireless network connection or backhaul infrastructure. In such cases, it is often advantageous for the compiler to reduce the size of the compiled code which must be downloaded to the wireless device. By reducing the size of the code needed to be downloaded, savings are achieved in terms of bandwidth required for each wireless point of download. Optimization metrics such as the memory system performance of compiled code are other metrics which are often important to developers. These are metrics correlated to the dynamic run-time behavior of not only the compiled code on the target processor, but also the underlying memory system, caches, DRAM and buses, etc. By efficiently arranging the data within the application or, more specifically, the order in which data and corresponding data structures are accessed by the application dynamically at run-time, significant performance improvements can be gained at the memory-system level. In addition, vectorizing compilers can also improve performance due to spatial locality of data when SIMD instruction sets are present and varying memory-system alignment conditions are met. When designing an embedded system, special care must be taken when you design the user interface. For simple devices, simple text, command buttons, and LEDs are adequate. For more complex systems, full graphical user interfaces and touch panels are required. User interface design focuses on the following key areas: (a) the design of interfaces between different software components, (b) the design of interfaces between the software and other nonhuman producers and consumers of information, and (c) the design of the interface between a human and the computer. This chapter will focus on the process, guidelines, human factors and techniques required to design an effective user interface. In this chapter, we cover the aspects of developing safety-critical software. The first part of the chapter covers project planning, and the core steps that are needed to scope the effort and getting started. It offers insights into managing safety-critical requirements and how to meet them during the development. Key strategies for project management are also provided. The second part of the chapter goes through an analysis of faults, failures, and hazards. It includes a description of risk analysis. The next part of the chapter covers a few safety-critical architectures that could be used for an embedded system. The final part of the chapter covers software implementation guidelines for safety-critical software development.
networking, to wireless base stations. This chapter is a summary of key sections of the recently released Multicore Programming Practices (MPP) from the Multicore Association (MCA). The MPP standardized “best practices” guide is written specifically for engineers and engineering managers of companies considering or implementing a development project involving multicore processors and favoring use of existing multicore technology. There is an important need to better understand how today’s C/C++ code may be written to be “multicore ready”, and this was accomplished under the influence of the MPP working group. The guide will enable you to (a) produce higher-performing software; (b) reduce the bug rate due to multicore software issues; (c) develop portable multicore code which can be targeted at multiple platforms; (d) reduce the multicore programming learning curve and speed up development time; and (e) tie into the current structure and roadmap of the Multicore Association’s API infrastructure.


The previous chapter approaches embedded systems from a higher level of abstraction; from the system design architecture and how to apply design patterns for the implementation. This chapter introduces two fundamental concepts and design patterns in real-time systems: (a) the ability to set asynchronous event flags (events) and (b) the ability to have things triggered in a timely fashion (triggers). These two concepts are used both in systems with a real-time operating system (RTOS) and in systems not using an RTOS. The chapter starts with use cases and then develops different ways to implement events and triggers. It presents different implementation details and discusses the advantages and disadvantages. The sources for both event and trigger implementation are provided at the end of the chapter. Code optimization is a critical step in the development process as it directly impacts the ability of the system to do its intended job. Code that executes faster means more channels, more work performed and competitive advantage. Code that executes in less memory enables more applications to be put on the same processor. Code that executes with less overall effort can reduce power consumption increases battery life or reduces money spent on powering a base station. This chapter is intended to help programmers write the most efficient code possible, whether that is measured in processor cycles, memory, or power. It starts with an introduction to using the tool chain, covers the importance of knowing the embedded architecture before optimization, then moves on to cover a wide range of optimization techniques. Techniques are presented which are valid on all programmable architectures – C-language optimization techniques and general loop transformations. Real-world examples are presented throughout.

When planning the development of modern embedded systems, hardware and software cannot be considered independently. Over the last two decades chip and system complexity has seen an enormous amount of growth, while more and more system functionality has moved from dedicated hardware implementation into software executing on general-purposed embedded processors. By 2010 the development software for hardware had outgrown the development efforts for hardware, and the complexity trend continues in favor of software. Traditional design techniques such as independent hardware and software design are being challenged due to heterogeneous models and applications being integrated to create a complex system on chip. Using proper techniques of hardware-software codesign, designers consider the trade-offs in the way hardware and software components of a system work together to exhibit a specified behavior, given a set of performance goals and technology. This chapter will cover these topics.

State of the art techniques and best practices in the development of embedded software apply not only to high-integrity devices (such as those found in critical applications like aircraft flight controllers, car braking systems or medical devices), but also to lesser-integrity applications when the need to optimize the effectiveness of the available test time and budget demands that pragmatic decisions should be made. To complement this multitude of software test techniques there is a similar plethora of test tools available to automate them. These tools are commonplace in the development of safety-critical applications but elsewhere not everyone has the budget to buy all, or indeed any, of them. Of course, the providers of these tools would advocate the purchase of each and every one of them, so how can a limited budget best be allocated? And where no budget exists, how can similar principles be applied to provide confidence that the finished item is of adequate quality? In addressing these issues not only are the concepts behind the techniques presented, but also some "case study" software code examples to drill a little deeper and illustrate how some of them are implemented in practice.

 Agile software development is a set of software development techniques based on iterative development. Requirements and software systems evolve through collaboration between self-organizing, cross-functional teams. Agile development supports adaptive planning, evolutionary development and delivery, and a time-boxed iterative approach. The goal of agile is rapid and flexible response to change. Agile is a conceptual framework which promotes interactions throughout the development cycle. Applying agile to embedded software projects introduces some unique challenges, such as more difficulty effectively testing evolving software features, because the corresponding hardware may not be available in time, less freedom to make changes, due to the fact that the corresponding hardware change may have an unacceptably high cost, and less ability for “learn as you go” approaches, considering the hardware construction may demand a more upfront style of planning and design. This chapter will introduce agile software development and show how to apply these techniques to an embedded system.

Intellectual property normally means one of two things – the patents or other legal protections you have accumulated to protect your inventions, or the inventions and designs themselves. So we may talk about “licensing one’s intellectual property”, and mean either selling a license to someone to make use of your patented ideas, or selling a license to build, distribute or use a product, as ARM does with its processor and other designs or a tools company does with its compiler and OS products. In this chapter, we will be concentrating more on the first meaning – dealing with the legal protections around your work – and we will be covering the basics in two major sections, one covering the issues surrounding what you need to do to be sure that you actually do own that software that you wrote or bought, what you need to do when selling it or licensing it to others, including the role of “open software”; and the other covering the various protections you can obtain for your software and any valuable inventions in it.

This chapter explores the unique challenges that limit reuse in embedded systems, and strategies to overcome them. It explores what limits reuse, and traditional approaches to overcome the limitations such as a hardware abstraction layer or an RTOS porting layer. It does not stop there. The shortcomings of layered software drive a desire for highly optimized
reusable software components. This chapter introduces the component factory concept: a mechanism that creates reconﬁgurable and reusable hardware- and RTOS-agnostic components generated by an expert system. Many systems, devices and appliances used routinely in everyday life, ranging from cell phones to cars, contain signiﬁcant amounts of software that is not directly visible to the user and is therefore called “embedded”. For coordinating the various software components and allowing them to communicate with each other, support software is needed, called an operating system (OS). Because embedded software must function in real time (RT), a RTOS is needed. This book describes a formally developed, network-centric Real-Time Operating System, OpenComRTOS. One of the ﬁrst in its kind, OpenComRTOS was originally developed to verify the usefulness of formal methods in the context of embedded software engineering. Using the formal methods described in this book produces results that are more reliable while delivering higher performance. The result is a unique real-time concurrent programming system that supports heterogeneous systems with just 5 Kbytes/node. It is compatible with safety related engineering standards, such as IEC61508.

This chapter introduces the automotive system, which is unlike any other, characterized by its rigorous planning, architecting, development, testing, validation and veriﬁcation. The physical task of writing embedded software for automotive applications versus other application areas is not signiﬁcantly different from other embedded systems, but the key differences are the quality standards which must be followed for any development and test project. To write automotive software the engineer needs to understand how and why the systems have evolved into the complex environment it is today. They must be aware of the differences and commonalities between the automotive submarkets. They must be familiar with the applicable quality standards and why such strict quality controls exist, along with how quality is tested and measured, all of which are described in this chapter with examples of the most common practices. This chapter introduces various processes to help software engineers write high-quality, fault-tolerant, interoperable code such as modeling, autocoding and advanced trace and debug assisted by the emergence of the latest AUTOSAR and ISO26262 standards, as well as more traditional standards such as AEC, OBD-II and MISRA.

Embedded systems often have one or more real-time requirements. The complexity of modern embedded software systems requires a systematic approach for achieving these performance targets. An ad hoc process can lead to missed deadlines, poorly performing systems and cancelled projects. There is a maturity required to deﬁne, manage, and deliver on multiple real-time performance requirements. Software performance engineering (SPE) is a discipline within the broader systems engineering area that can improve the maturity of the performance engineering process. SPE is a systematic, quantitative approach to constructing software systems that meet performance objectives. SPE is a software-oriented approach; it focuses on architecture, design, and implementation choices. It focuses on the activities, techniques, and deliverables that are applied at every phase of the embedded software development life-cycle, especially responsiveness and scalability, to ensure software is being architected and implemented to meet the performance-related requirements of the system.

Offering comprehensive coverage of the convergence of real-time embedded systems scheduling, resource access control, software design and development, and high-level system modeling, analysis and veriﬁcation Following an introductory overview, Dr. Wang delves into the specifics of hardware components, including processors, memory, I/O devices and architectures, communication structures, peripherals, and characteristics of real-time operating systems. Later chapters are dedicated to real-time task scheduling algorithms and resource access control policies, as well as priority-inversion control and deadlock avoidance. Concurrent system programming and POSIX programming for real-time systems are covered, as are ﬁnite state machines and Time Petri nets. Of special interest to software engineers will be the chapter devoted to model checking, in which the author discusses temporal logic and the NuSMV model checking tool, as well as a chapter treating real-time software design with UML. The ﬁnal portion of the book explores practical issues of software reliability, aging, rejuvenation, security, safety, and power management. In addition, the book: Explains real-time embedded software modeling and design with ﬁnite state machines, Petri nets, and UML, and real-time constraints veriﬁcation with the model checking tool, NuSMV Features real-world examples in ﬁnite state machines, model checking, real-time system design with UML, and more Covers embedded computer programming, designing for reliability, and designing for safety Explains how to make engineering trade-offs of power use and performance Investigates practical issues concerning software reliability, aging, rejuvenation, security, and power management Real-Time Embedded Systems is a valuable resource for those responsible for real-time and embedded software design, development, and management. It is also an excellent textbook for graduate courses in computer engineering, computer science, information technology, and software engineering on embedded and real-time software systems, and for undergraduate computer and software engineering courses. A recent survey stated that 52% of embedded projects are late by 4-5 months. This book can help get those projects in on-time with design patterns. The author carefully takes into account the special concerns found in designing and developing embedded applications speciﬁcally concurrency, communication, speed, and memory usage. Patterns are given in UML (Unifed Modeling Language) with examples including ANSI C for direct and practical application to C code. A basic C knowledge is a prerequisite for the book while UML notation and terminology is included. General C programming books do not include discussion of the contraints found within embedded system design. The practical examples give the reader an understanding of the use of UML and OO (Object Oriented) designs in a resource-limited environment. Also included are two chapters on state machines. The beauty of this book is that it can help you today. . Design Patterns within these pages are immediately applicable to your project Addresses embedded system design concerns such as concurrency, communication, and memory usage Examples contain ANSI C for ease of use with C programming code
Real-time operating systems (RTOS) are ubiquitous in embedded systems. This chapter explains what a real-time kernel is and what services it provides the product developer, and explains some of the internals of a kernel. A kernel is a component of an RTOS. In this chapter, we'll look at task management, interrupt handling, scheduling, context switching, time management, resource management, message passing, priority inversions and much more.

Creating a model for your embedded system provides a time- and cost-effective approach to the development of simple or incredibly complex dynamic control systems, all based on a single model maintained in a tightly integrated software suite. Using modern modeling software tools you can design and perform initial validation in off-line simulation. These models then form the basis for all subsequent development stages. Creating models for your embedded design provides numerous advantages over the traditional design approach. Using this approach – combined with hardware prototyping – you reduce the risk of mistakes and shorten the development cycle by performing verification and validation testing throughout the development instead of only during the final testing stage. Design evaluations and predictions can be made much more quickly and reliably with a system model as a basis. This iterative approach results in improved designs, in terms of both performance and reliability. The cost of resources is reduced, because of reusability of models between design teams, design stages, and various projects and the reduced dependency on physical prototypes.

Development errors and overhead can be reduced through the use of automatic code-generation techniques. These advantages translate to more accurate and robust control designs, shorter time to market, and reduced design cost. Das Buch beschreibt den objektorientierten Entwurf von Software-/Hardware-Lösungen zu automatisierungstechnischen Problemlösungen, sogenannten "embedded systems". Objektorientierte Systeme bieten erhebliche Vorteile bei der Beherrschung von Komplexität, späteren Änderungen und Wartungsmaßnahmen. Ausgehend von bekannten Analyse- und Designmethoden werden zunächst die grundlegenden objektorientierten Konzepte vorgestellt, ausgewählte Methoden im Überblick miteinander verglichen und die speziellen Eigenschaften von "embedded systems" beschrieben. Der Autor entwickelt dann mittels Zustands-Übergangsdiagrammen eine Methode für objektorientierte Spezifikation. Damit kann ein tragfähiger, stabiler Entwurf formuliert werden, der direkt in einer objektorientierten Programmiersprache implementierbar ist.

Software Engineering for Embedded Systems: Methods, Practical Techniques, and Applications, Second Edition provides the techniques and technologies in software engineering to optimally design and implement an embedded system. Written by experts with a solution focus, this encyclopedic reference gives an indispensable aid on how to tackle the day-to-day problems encountered when using software engineering methods to develop embedded systems. New sections cover peripheral programming, Internet of things, security and cryptography, networking and packet processing, and hands on labs. Users will learn about the principles of good architecture for an embedded system, design practices, details on principles, and much more. Provides a roadmap of key problems/issues and references to their solution in the text Reviews core methods and how to apply them Contains examples that demonstrate timeless implementation details Users case studies to show how key ideas can be implemented, the rationale for choices made, and design guidelines and trade-offs.

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This Expert Guide gives you the techniques and technologies in software engineering to optimally design and implement your embedded system. Written by experts with a solutions focus, this encyclopedic reference gives you an indispensable aid to tackling the day-to-day problems when using software engineering methods to develop your embedded systems. With this book you will learn: The principles of good architecture for an embedded system Design practices to help make your embedded project successful Details on principles that are often a part of embedded systems, including digital signal processing, safety-critical principles, and development processes Techniques for setting up a performance engineering strategy for your embedded system software How to develop user interfaces for embedded systems Strategies for testing and deploying your embedded system, and ensuring quality development processes Practical techniques for optimizing embedded software for performance, memory, and power Advanced guidelines for developing multicore software for embedded systems How to develop embedded software for networking, storage, and automotive segments How to manage the embedded development process Includes contributions from: Frank Schirmeister, Shelly Grettlein, Bruce Douglass, Erich Styger, Gary Stringham, Jean Labrosse, Jim Trudeau, Mike Brogioni, Mark Pitchford, Catalin Dan Udima, Markus Levy, Pete Wilson, Whit Waldo, Inga Harris, Xinxin Yang, Srinivasa Addepalli, Andrew McKay, Mark Kraeiling and Robert Oshana. Road map of key problems/issues and references to their solution in the text Reviews of core methods in the context of how to apply them Examples demonstrating timeless implementation details Short and to-the-point case studies to show how key ideas can be implemented, the rationale for choices made, and design guidelines and trade-offs.

Embedded networking applications are changing and evolving quickly. Embedded multicore technology, for example, is appearing not only in high-end networking applications, but even in mid- and low-end networking applications. Achieving networking performance is only possible if software takes advantage of multiple cores. Multicore programming is not as simple as single-core programming. A new mindset is required, from architecting, designing to coding. Networking application development in multicore SoCs should not only concentrate on achieving scalable performance, but should also ease development and result in software that is maintainable for a long time. Some of the programming techniques listed in this chapter should help in achieving this goal.

This book provides a good opportunity for software engineering practitioners and researchers to get in sync with the current state-of-the-art and future trends in component-based embedded software research. The book is based on a selective compilation of papers that cover the complete component-based embedded software spectrum, ranging from methodology to tools. Methodology aspects covered by the book include functional and non-functional specification, validation, verification, and component architecture. As tools are a critical success factor in the transfer from academia-generated knowledge to industry-ready technology, an important part of the book is devoted to tools. This state-of-the-art survey contains 16 carefully selected papers organised in topical sections on specification and verification, component compatibility, component architectures, implementation and tool support, as well as non-functional properties.